

# DOCOMO's Views and Activities for LTE/5G Connected Car

Takehiro Nakamura
5G Laboratory, NTT DOCOMO



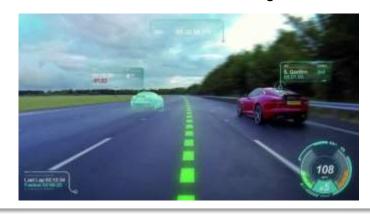
# Connected Car Use case and Requirements

# Use cases



#### **Assisted driving**

Navigation, see-through, hazards, vulnerable road user warning, etc.



#### **Autonomous driving**

Partial ~ fully autonomous/ cooperative driving (highways, traffic jams, parking, platooning,



## **Tele-operated driving**

Remote operations in case of troubles, remote driving at disaster/ dangerous areas (mines, construction sites, power plants, etc.)



#### Info-mediation

Value creation by processing various information Security (theft tracking, border control), safety (eCall, bCall), fleet management (car share,



#### Infotainment

Entertainment (video, VR, AR)
Productivity (video conferencing, in-vehicle



#### **Nomadic nodes**

Cellular capacity/ coverage expansion using moving small cells on vehicles



Reference: http://ngmn.org/uploads/media/160922\_NGMN\_-\_Perspectives\_on\_Vertical\_Industries\_and\_Implications\_for\_5G\_final.pdf Image sources (left top to right bottom): Jaguar Land Rover, Volkswagen, Verbundprojekt Vision TUM, erpfm.com, Mercedes Benz, BMW

# Use cases



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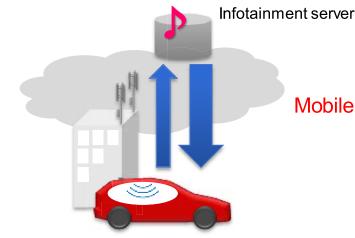
# 1. Infotainment



#### Use case

- In-vehicle entertainment (video, VR, AR, etc.)
- Productivity (video conferencing, in-vehicle office)
  - Improved productivity is one of the main motivations for purchasing autonomous driving\*

#### Requirements



For high speed/ capacity services, Mobile broadband backhaul (5~10 Gb/s) is needed.

Coverage is crucial.

#### **Solutions**

- ~1 Gb/s is possible with LTE/ LTE-A, but 5G can enable higher data rates and capacity.
- Massive MIMO can be exploited using larger rooftop antennas.
- Use of WiFi can be considered for in-vehicle access, to cater for various passengers.

- Mobility support in case of using mmWave or small cells.
- Attractive value proposition to the customers.

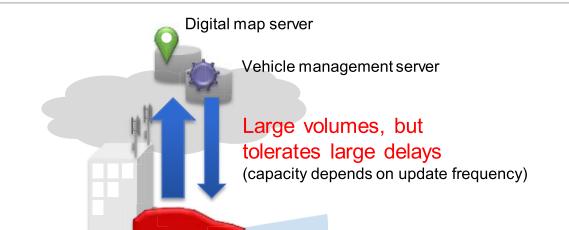
# 2. Digital map/ vehicle management



#### Use case

- Sensor data collection for 3D digital map update at the server side (UL)
- On-board 3D digital map update (DL)
- Vehicle diagnostics reporting (UL)
- On-board software update (DL)

# Requirements



Automobile companies would want to realise applications agnostic to the underlying connectivity layer

(avoid specific implementations for each country/ telecom provider)

#### **Solutions**

- Application control (time triggers, location triggers)
- Existing networks can be good, but e.g., split charging, network slicing may be useful.

- Capacity provisioning, application control vs network control
- Realising a global solution

# 3. Remote operations



#### Use case

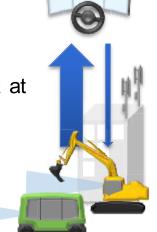
- Remote control of vehicles in case of troubles (safe stopping, system reset)
- Remote driving at disaster/ dangerous areas (mine, construction site, power plants, etc.)
  - Places where autonomous algorithms cannot work effectively and need manual manoeuvre

# Requirements

UL: Recreation of driving environment at remote booth

→ High data rate,

low latency



DL: Remote control

→ Narrow band, low latency, high reliability

#### Example:

- 30 km/h → 1 m/ 120 ms
- UL: 60 fps video → 16.7 ms
- DL: 20 Hz control → 50 ms



RTT <50 ms

#### **Solutions**

- Cellular is good, but need e.g., diversity, QoS control, wider bandwidth, etc. to improve reliability
- For safety, operations may need to be limited to low speeds (<30 km/h) or cases without passengers.

- Certification (remote booth, remote driver, telecom system)
- Liability in case of accidents

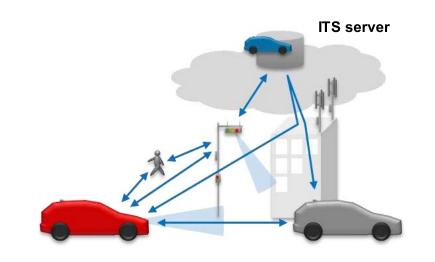
# 4. Driving assistance



#### Use case

- Environment recognition (driving assistance)
- Distribution of hazard information, vulnerable road user warning
- Sharing of driving intentions and control information

#### Requirements



- Environment recognition and driving intention sharing requires stringent latency and reliability.
- Broadband for wide area recognition to improve comfort and traffic efficiency.

#### **Solutions**

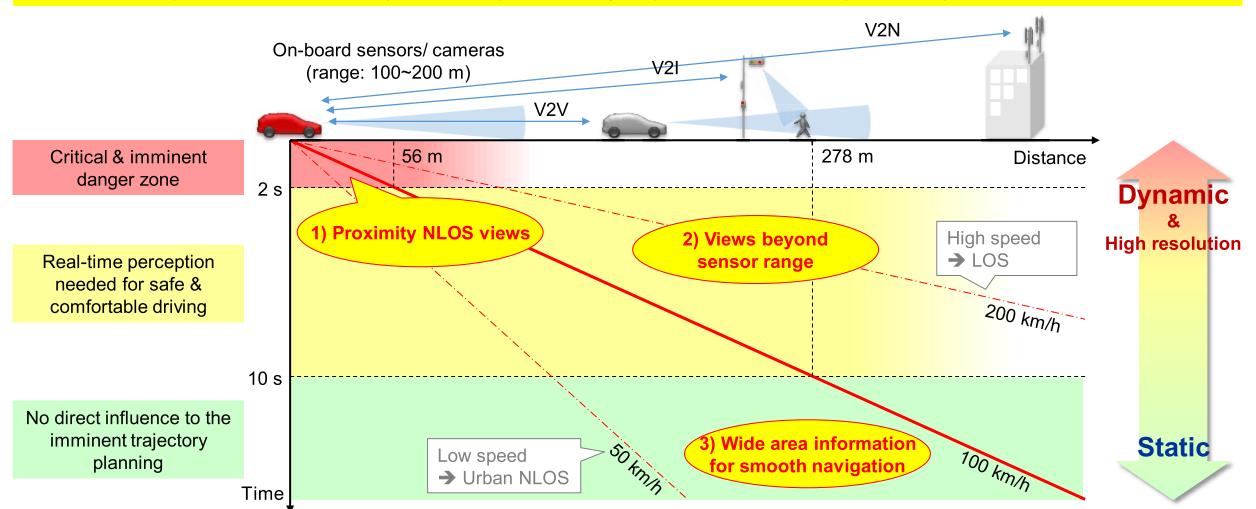
 Compound use of V2V, V2I, V2N and V2P depending on the use case and environment/ situation.

- Clarification on the necessary composition of V2V, V2I, V2N and V2P
- Spectrum, business models

# Potential areas of connectivity support for environment perception



While on-board sensors/ cameras will play the core role for environment perception, connectivity can support for 1) proximity NLOS, 2) beyond sensor range, and 3) wide area information.



# Valid range and expiry time of distributed information



# Distributed information has "valid range" and "expiry time" depending on the contents and velocity.

	Distributed information	Data rate
Dynamic	Coordinated control (negotiation)	~2.5 Mb/s x #vehicles
information	Sensor/ video/ object data  Depth, video, 3D grid occupancy, detected object data, etc.  Source: on-board sensors, RSU sensors  Distribution of aggregated data could also be considered	0.5~50 Mb/s x #vehicles (depending on the contents)
	Planned trajectory	~12.5 Mb/s x #vehicles
	Simple intention  • Lane change, braking, etc.	~50 kb/s x #vehicles
	Traffic signal information	~1 kb/s x #signals
Semi-dynamic information	Accidents, traffic jam, parking lots, local proximity weather, etc.	
Semi-static information	Construction, road closure, wide area weather, etc.	
Static information	Road surface, lanes, structures, road side facilities, etc.  * Some overlap with "2. Map/ vehicle management"	

Valid range	<b>Expiry time</b>
50 m	100 ms ≀ 1 s
300 m	1 s ≀ 1 month

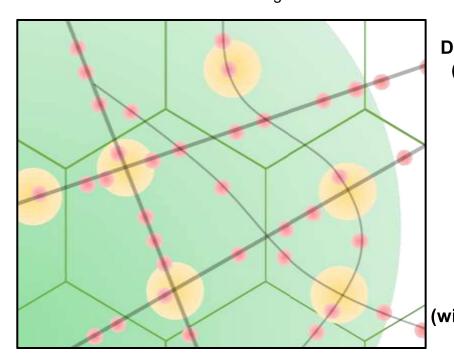
# Positioning of technologies for information

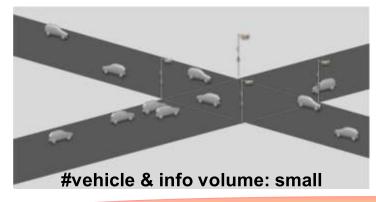


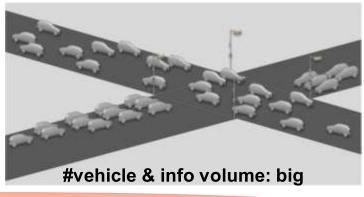
distribution platform

Platform design needs to consider valid range, expiry time, #vehicles, and data volume of the distributed information

\* Need to consider the difference in cell size and the relevant radius for distributing information.







Osrc / ITS

(on-board sensors)

latency <20 ms, range & capacity expansion

**Direct V2X** 

**5G** further low latency, high reliability & capacity

Densification (RSU, sectorization)

Content optimization by location/ direction

S<mark>tati</mark>c (wide area)

**Existing cellular (unicast)** 

avg latency ~50 ms

**Multicast** 

larger #devices & capacity

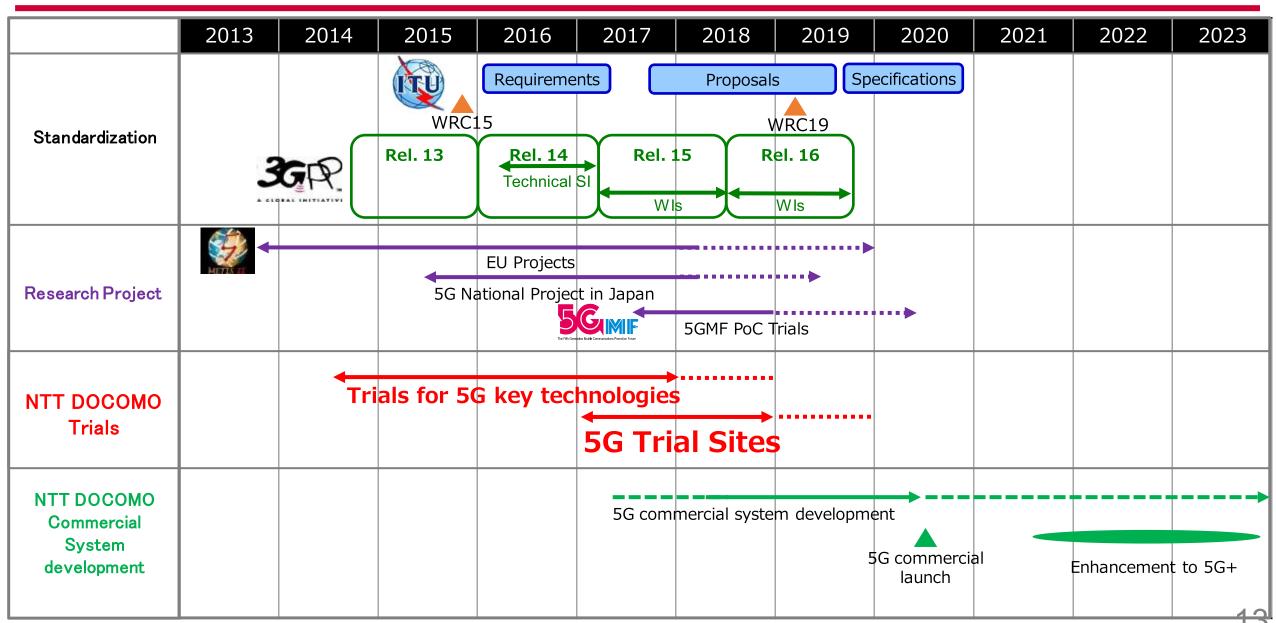
Time shifting traffic normalization



# DOCOMO's Activities for LTE/5G Connected Car

# Time schedule for 5G deployment in 2020

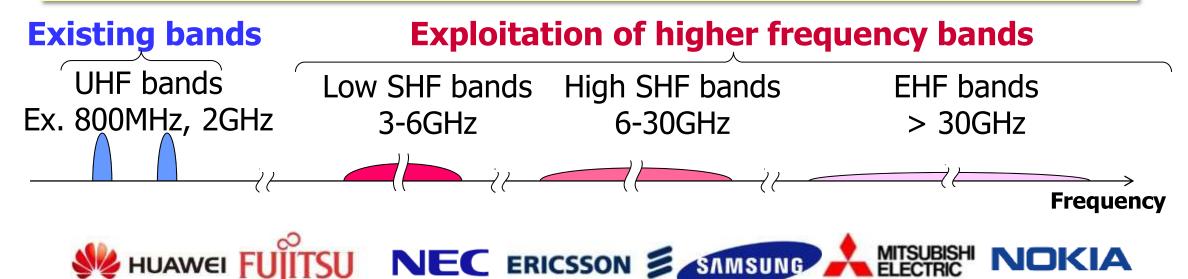




# 5G Experimental Trials [w/ 13 vendors]



5G experimental trials are being started since Q4 of 2014



Key devices/Chip sets vendors

System solution vendors

Measuring instruments vendors







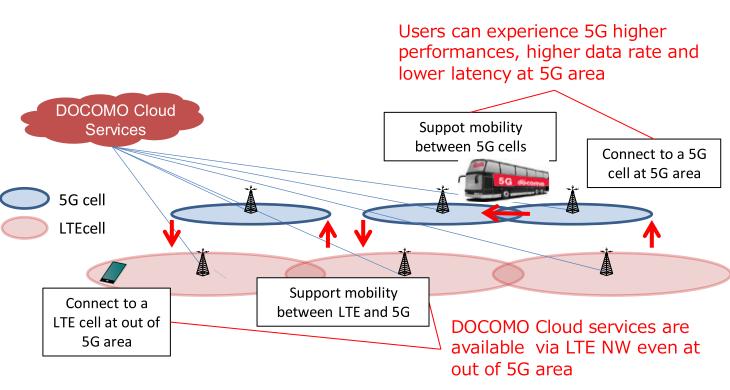


# NTT DOCOMO 5G Trial Sites



# The 5G Trial Sites are offered in two distinct of Tokyo, the Odaiba waterfront and Tokyo SKYTREE TOWN from May, 2017



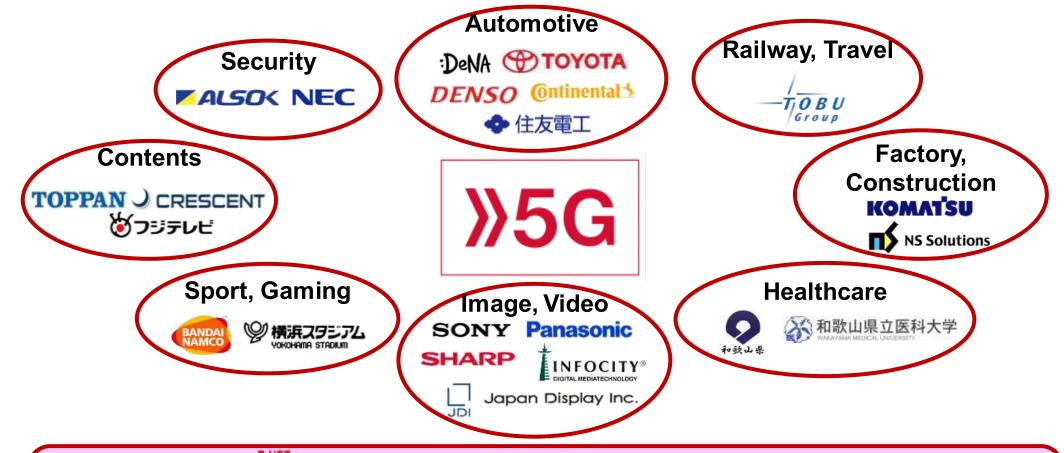


Support mobility between 5G and commercial LTE NW Utilize 28 GHz and 4.5 GHz frequency bands

# Collaboration with Vertical Industries for 5G Service Creation



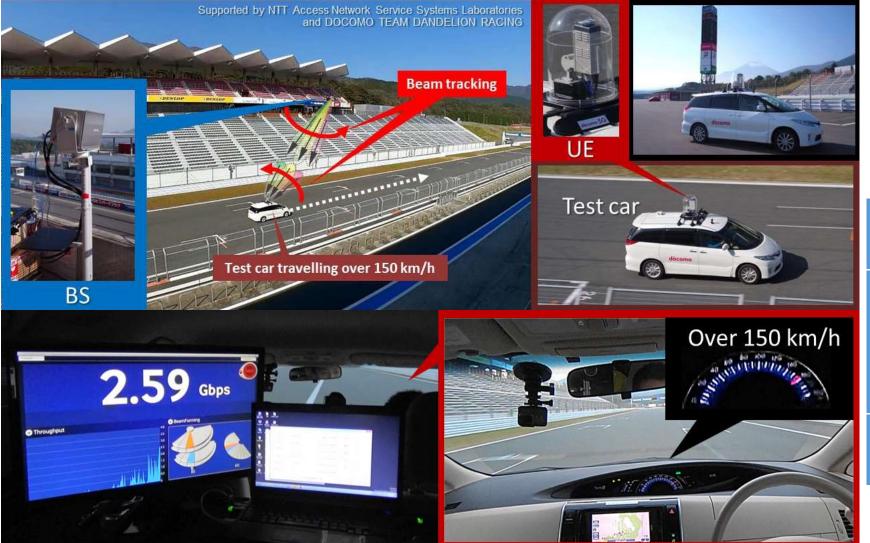
- To create excellent 5G services, DOCOMO is collaborating with many partners of variety of vertical industries
- DOCOMO intend to expand collaborations for 5G service co-creation



# Samsung @ 28 GHz 5G High Mobility Test in Fuji Speedway



We have successfully achieved a data speed of more than 2.5 Gbps on a vehicle travelling at a speed over 150 km/h



#### Major specifications

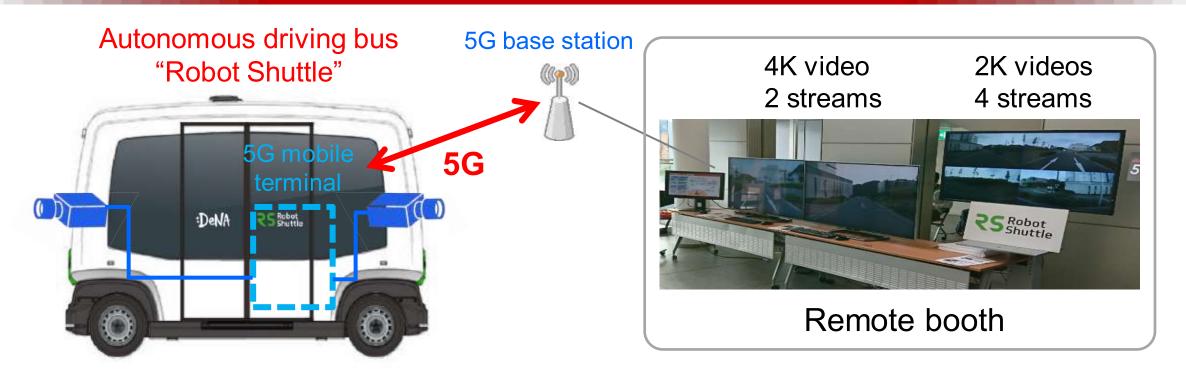
Freq.	28 GHz band	
band	(800 MHz bandwidth)	
BS	•96 antenna elements	
	•support up to 2 stream	
	MIMO transmission with 2	
	beams	
UE	•8 antenna elements	
	•2 beams reception	

# Remote monitoring of autonomous vehicles using 5G Joint project with DeNA



- Remote monitoring system trial jointly with DeNA
- Transmission of realtime videos to the remote operation centre using 5G
- Transmission of multiple high resolution video streams by 5G enables quick responses upon emergency events

# Demo at NTT DOCOMO R&D Open House (Nov 2016)



## Video chat service using 5G Joint project with Continental Automotive



- Joint trials with Continental Automotive on connected car infotainment services.
- Exhibited a video chat system at 5G Tokyo Bay Summit in May 2017, using 5G connections between the exhibition sites and the moving vehicle at a remote area (at DOCOMO's R&D Center).

# **Demo at 5G Tokyo Bay Summit (May 2017)**

NTT DOCOMO R&D Center (YRP)

Using 5G connection to the vehicle





5G base station



#### Future construction sites realized by 5G

# - To realize future ICT construction -



To realize a remote operating system for construction/mining machines leveraging the high-speed and low-latency characteristics of the 5G radio technology KOMATSU

#### **≫** Features

- Remote in-depth monitoring of the construction site by five high-definition video streams transmitted via the high-speed broadband capability of 5G
- High-precision operation by leveraging the low-latency capability of 5G
- By setting up 5G base stations at dangerous disaster aftermath, remote operation of heavy machinery can be rapidly provisioned



# Demonstration of 5G connected cars



Real-time video streaming demonstrations of 5G connected cars, by collaboration with Intel, Ericsson, Denso and Toyota

TOYOTA







#### **≫** Features

- Transmission of rich contents (i.e., diagnostics, 4K videos, etc.) by 5G with TOYOTA ALPHARD driving in the Odaiba area.
- Demonstration of 5G performance dynamics and beam tracking capability through the original visualization system.



Base station Antenna



TOYOTA ALPHARD mounted with 5G mobile equipment



## Providing new moving experience of the 5G era

# New concept cart



Being inspired by the fact that mobile phones have evolved into smartphones by adopting various sensors and interfaces, we have evolved smartphones and realized a new concept vehicle by employing SONY's technologies and designs SONY

#### **≫** Features

- Displaying on a 4K-drive display, 360°-view videos taken by a camera sensor with ultra-high sensitivity beyond that of human eyes
- Communications employing 4K Digital Signage & communication display

#### Main function

- 4K ultra high sensitive camera sensor & drive display
- 360-degree view system
- Digital Signage x 6
- Olivine-type lithium-ion rechargeable battery
- Ultrasonic sensor
- Control with game controller



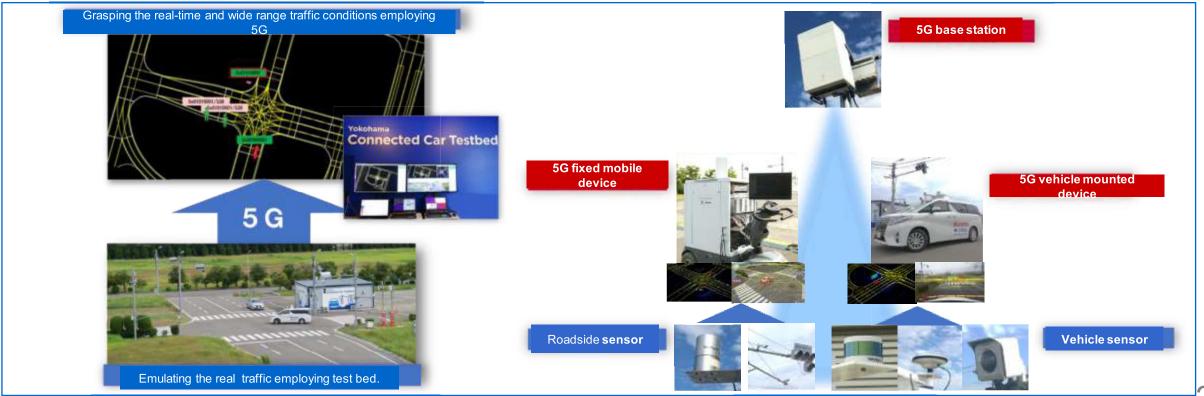
# Demonstration targeting use of road traffic condition data employing 5G Real-time data collection and analysis of road traffic conditions



Real-time data collection and analysis of road traffic conditions employing 5G; the next generation radio system, and sensors embedded in the traffic infrastructures such as vehicles, roads and buildings

#### **≫** Features

- Employing 5G, featuring high-speed, broadband and low-latency
- Collection and analysis of traffic condition data of the surrounding environment such as driving vehicles, pedestrians, and road traffic conditions
- Grasping real-time and wide-range traffic conditions and providing advanced support for vehicles and pedestrians



# Synchronized TV broadcasting & real-time AR



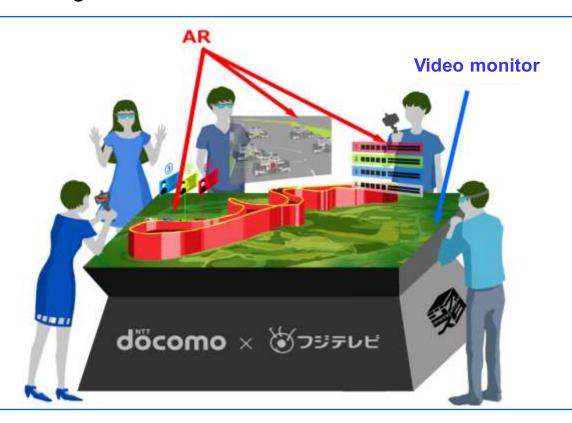
"Dio-stadium" introduces new viewing experience by AR! A new form of watching sports broadcast is proposed



#### **≫** Features

- New user experience by real-time AR; enables arbitrary viewpoints to watch sports games
- AR indication of information linked to TV broadcasting

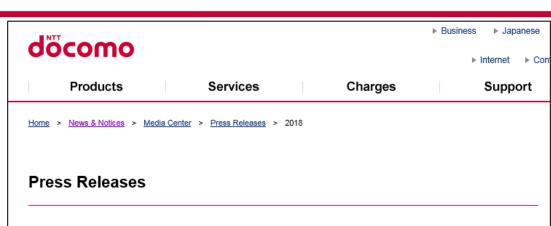
By projecting videos taken in Suzuka Circuit on the 55-inch 4-screen monitor, users can enjoy formula car racing on their devices in 3D



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# Celluler V2X Trial Collaboration





January 12, 2018

# Leading Automotive, Telecom and ITS Companies Unveil First Announced Cellular V2X Trials in Japan

— Continental, Ericsson, Nissan, NTT DOCOMO, OKI and Qualcomm Technologies join forces to host C-V2X trials in Japan in 2018 to validate and demonstrate C-V2X benefits —







TOKYO, JAPAN, January 12, 2018 --- Continental, Ericsson, Nissan, NTT DOCOMO, INC., OKI and Qualcomm Technologies, Inc., a subsidiary of Qualcomm Incorporated (NASDAQ: QCOM), announced today plans to carry out their first Cellular Vehicle-to-Everything (C-V2X) trials in Japan. The objective is to validate and demonstrate the benefits of C-V2X using direct communication technology defined by the 3rd Generation Partnership Project (3GPP) in their Release 14 specifications. The trials are designed to show the enhanced range, reliability and latency benefits of C-V2X direct communications operated in 5 GHz band. Additionally, the C-V2X Trials are designed to demonstrate the complementary benefits of network-based communications utilizing LTE-Advanced (LTE-A). The trial results will help develop the ecosystem by providing inputs to the relevant stakeholders, including ITS-related organizations and government agencies, as we prepare for the connected car of the future and the industry's evolutionary transition towards 5G New Radio (NR), the new global cellular standard being defined in 3GPP.

While complementing other Advanced Driver Assistance System (ADAS) sensors, such as radar, lidar, and camera systems, C-V2X provides non-line-of-sight (NLOS) low latency awareness with longer range and cloud capabilities, and is designed to extend a vehicle's ability to see, hear and communicate further down the road, even at blind intersections.





# Thank you for your attention!



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